



# ADVANCED MATHEMATICS

Final Exam - June 2013

Name: \_\_\_\_\_

NIU: \_\_\_\_\_ Group: \_\_\_\_\_

Grade: \_\_\_\_\_

**Instructions:** The exam consists of six questions. You have two hours to give a reasoned answer to all the exercises. Write the quiz entirely in ink.

- 1 Determine for which values of the parameter  $a \in \mathbb{R}$  the matrix  $A$  is diagonalizable.

$$A = \begin{pmatrix} 0 & 0 & a \\ 1 & 1 & 1 \\ 1 & 0 & 0 \end{pmatrix}$$

- 2 Determine whether the following statement is true. If it is, provide a reasoned argument. If it is not, show a counterexample: "If  $A$  is a matrix whose determinant is equal to zero, then  $A$  is NOT diagonalizable."

3 Solve the system of difference equations

$$X_{t+1} = AX_t,$$

where  $A$  is the matrix of Exercise 1 when  $a = 4$ . Is this system globally asymptotically stable? Is there any initial condition  $X_0$  such that the solution converges?

4 Solve the following differential equation:

$$x' = -\frac{2t + 3x}{3t + 2x},$$

where  $x(1) = 1$ .

5 Obtain the solutions of the following differential equation:

$$x''' - 3x'' + 3x' - x = t^2$$

6 Obtain the solution to the following system:

$$X' = \begin{pmatrix} -3 & 0 \\ 0 & 1 \end{pmatrix} X + \begin{pmatrix} e^t \\ 1 \end{pmatrix},$$



**Instructions:** The exam consists of six questions. You have two hours to give a reasoned answer to all the exercises. Write the quiz entirely in ink.

- 1 Determine for which values of the parameter  $a \in \mathbb{R}$  the matrix  $A$  is diagonalizable.

$$A = \begin{pmatrix} 0 & 0 & a \\ 1 & 1 & 1 \\ 1 & 0 & 0 \end{pmatrix}$$

**Solution.** The eigenvalues of  $A$  are  $\sigma(A) = \{1, +\sqrt{a}, -\sqrt{a}\}$ . If  $a \in \mathbb{R}_-$  then the characteristic polynomial has complex roots and  $A$  is not diagonalizable. If  $a \in \mathbb{R}_+ \setminus \{0, 1\}$  then the three roots are real and different each other and  $A$  is diagonalizable. We study the other two cases:

- (a) If  $a = 0$ . Then  $\sigma(A) = \{1, 0\}$  with  $m(1) = 1$  and  $m(0) = 2$ . On the other hand,  $\dim \mathcal{S}(0) = 3 - \text{rank}(A - 0 \cdot I_3) = 3 - 2 = 1$ . Since the dimension of the eigenspace and the multiplicity do not coincide, the matrix  $A$  is not diagonalizable.
- (b) If  $a = 1$ . Then  $\sigma(A) = \{1, -1\}$  with  $m(1) = 2$  and  $m(-1) = 1$ . We compute the dimensions of the eigenspaces  $\dim \mathcal{S}(1) = 3 - \text{rank}(A - 1 \cdot I_3) = 3 - 2 = 1$  and  $\dim \mathcal{S}(-1) = 3 - \text{rank}(A + 1 \cdot I_3) = 3 - 2 = 1$ . Since  $\dim \mathcal{S}(1) \neq m(1)$ , the matrix  $A$  is not diagonalizable.

- 2 Determine whether the following statement is true. If it is, provide a reasoned argument. If it is not, show a counterexample: "If  $A$  is a matrix whose determinant is equal to zero, then  $A$  is NOT diagonalizable."

**Solution.** The statement is false. The following matrix (the null matrix) has a determinant equal to zero and it is diagonalizable (indeed, it is diagonal).

$$A = \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}$$

- 3 Solve the system of difference equations

$$X_{t+1} = AX_t,$$

where  $A$  is the matrix of Exercise 1 when  $a = 4$ . Is this system globally asymptotically stable? Is there any initial condition  $X_0$  such that the solution converges?

**Solution.** When  $a = 4$ ,  $\sigma(A) = \{1, 2, -2\}$ , and  $\mathcal{S}(1) = \langle (0, 1, 0) \rangle$ ,  $\mathcal{S}(2) = \langle (2, 3, 1) \rangle$  and  $\mathcal{S}(-2) = \langle (-6, 1, 3) \rangle$ . The system is homogeneous, and therefore

$$X_t = A_0 1^t \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} + A_1 2^t \begin{pmatrix} 2 \\ 3 \\ 1 \end{pmatrix} + A_2 (-2)^t \begin{pmatrix} -6 \\ 1 \\ 3 \end{pmatrix}$$

Since not all the eigenvalues are smaller than 1, the system is not globally asymptotically stable. On the other hand, the solution will converge for an initial condition  $X_0$  only if  $A_1 = A_2 = 0$

$$\begin{pmatrix} a \\ \beta \\ \gamma \end{pmatrix} = X_0 = A_0 1 \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} + 0 \begin{pmatrix} 2 \\ 3 \\ 1 \end{pmatrix} + 0 \begin{pmatrix} -6 \\ 1 \\ 3 \end{pmatrix} \Leftrightarrow a = \gamma = 0.$$

For  $X_0 = (0, 1, 0)$ , for example, the solution converges.

- 4 Solve the following differential equation:

$$x' = -\frac{2t + 3x}{3t + 2x},$$

where  $x(1) = 1$ .

**Solution.** It is an exact equation whose canonical form is  $(2t + 3x)dt + (2x + 3t)dx = 0$ . In this case,  $P(t, x) = 2t + 3x$  and  $Q(t, x) = 2x + 3t$ . We check the condition to be exact:

$$\frac{\partial P}{\partial x} = 3 = \frac{\partial Q}{\partial t}.$$

- Let  $F(t, x)$  be the solution of the equation we are looking for.
- Impose that

$$\frac{\partial F(t, x)}{\partial t} = P(t, x) \Rightarrow \frac{\partial F(t, x)}{\partial t} = 2t + 3x,$$

by integrating both sides with respect to  $t$ , we can isolate  $F(t, x)$ .

$$F(t, x) = t^2 + h(x).$$

- Now, impose that

$$\frac{\partial F(t, x)}{\partial x} = Q(t, x) \Leftrightarrow h'(x) = 2x + 3t.$$

- To obtain  $h(x)$ , simply integrate.

$$h(x) = x^2 + 3tx.$$

- Substitute  $h(x)$  in the expression of Step 2, and then:

$$F(t, x) = t^2 + x^2 + 3tx.$$

- The solution to the exact equation is given in implicit form:

$$t^2 + x^2 + 3tx = C$$

Now, we impose the initial condition  $x(1) = 1$  to obtain that  $C = 5$ . Therefore, the solution is  $t^2 + x^2 + 3tx = 5$ .

**5** Obtain the solutions of the following differential equation:

$$x''' - 3x'' + 3x' - x = t^2$$

**Solution.** The roots of the characteristic polynomial are  $r = 1$  with  $m(1) = 3$ . Then,

$$x^h(t) = A_0 e^t + A_1 t e^t + A_2 t^2 e^t$$

Since  $b(t) = t^2$  is a polynomial of degree 2, we propose  $x(t) = C_0 + C_1 t + C_2 t^2$ . Taking derivatives and substituting we get that  $C_0 = -12$ ,  $C_1 = -6$ , and  $C_2 = -1$ . And then,

$$x^p(t) = -12 - 6t - t^2$$

Finally

$$x(t) = A_0 e^t + A_1 t e^t + A_2 t^2 e^t - 12 - 6t - t^2$$

**6** Obtain the solution to the following system:

$$X' = \begin{pmatrix} -3 & 0 \\ 0 & 1 \end{pmatrix} X + \begin{pmatrix} e^t \\ 1 \end{pmatrix},$$

**Solution.** The matrix  $A$  of the system is already diagonal, hence,  $D$  is the  $A$  and  $P = P^{-1} = I_2$ , which implies that the solution to the associated homogeneous system is:

$$X^h(t) = K_0 e^{-3t} \begin{pmatrix} 1 \\ 0 \end{pmatrix} + K_1 e^t \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$



In order to obtain a particular solution, we solve the system

$$K'_0 e^{-3t} \begin{pmatrix} 1 \\ 0 \end{pmatrix} + K'_1 e^t \begin{pmatrix} 0 \\ 1 \end{pmatrix} = \begin{pmatrix} e^t \\ 1 \end{pmatrix} \equiv K'_0 = e^{4t} \text{ and } K'_1 = e^{-t} \equiv K_0 = \frac{1}{4} e^{4t} \text{ and } K_1 = -e^{-t}$$

Then, a particular solution is

$$X^p(t) = \frac{1}{4} e^{4t} e^{-3t} \begin{pmatrix} 1 \\ 0 \end{pmatrix} + -e^{-t} e^t \begin{pmatrix} 0 \\ 1 \end{pmatrix} = \begin{pmatrix} \frac{1}{4} e^t \\ -1 \end{pmatrix}$$

Finally,

$$X(t) = K_0 e^{-3t} \begin{pmatrix} 1 \\ 0 \end{pmatrix} + K_1 e^t \begin{pmatrix} 0 \\ 1 \end{pmatrix} + \begin{pmatrix} \frac{1}{4} e^t \\ -1 \end{pmatrix}$$